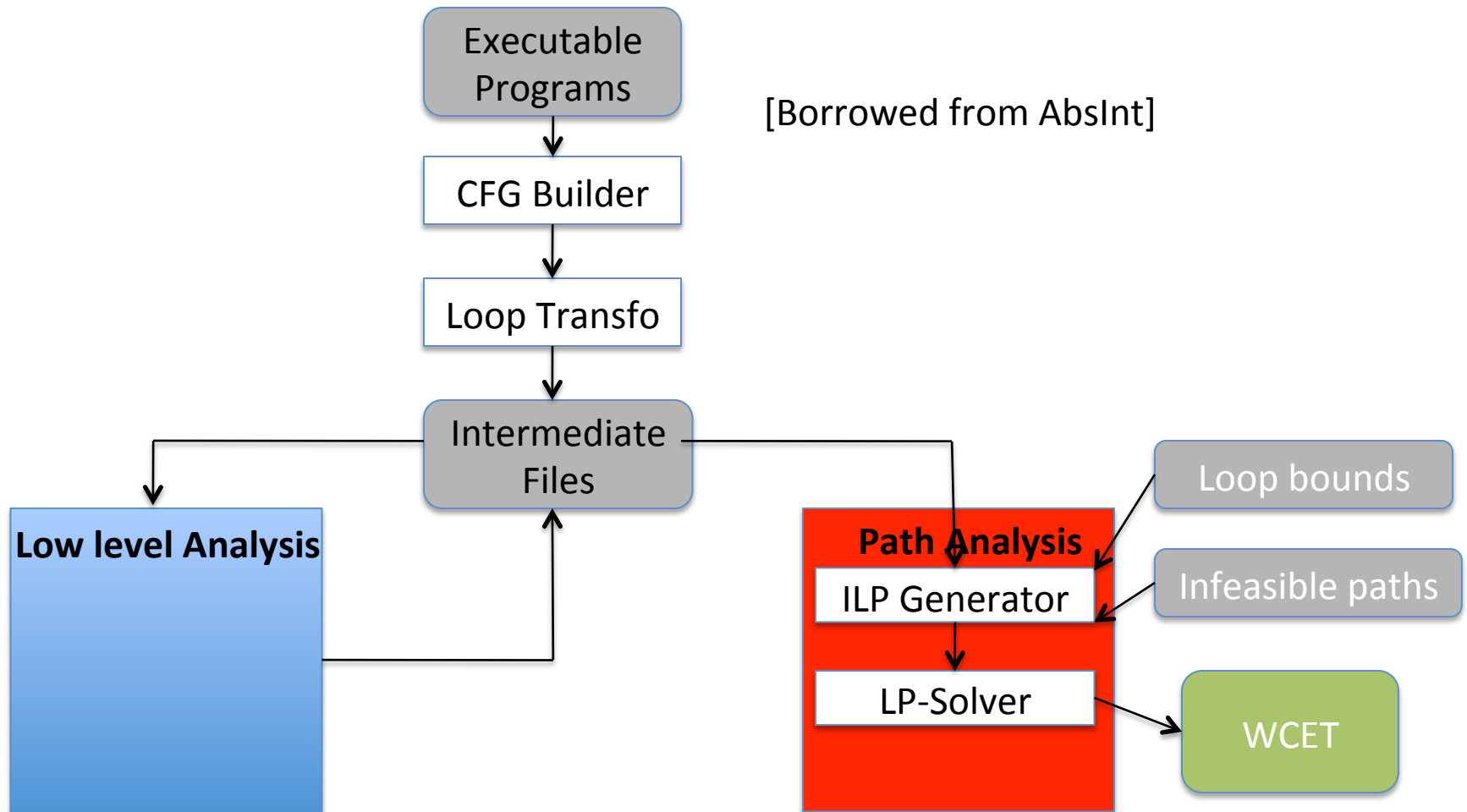


Symbolic Simulation on Complicated Loops for WCET Path Analysis

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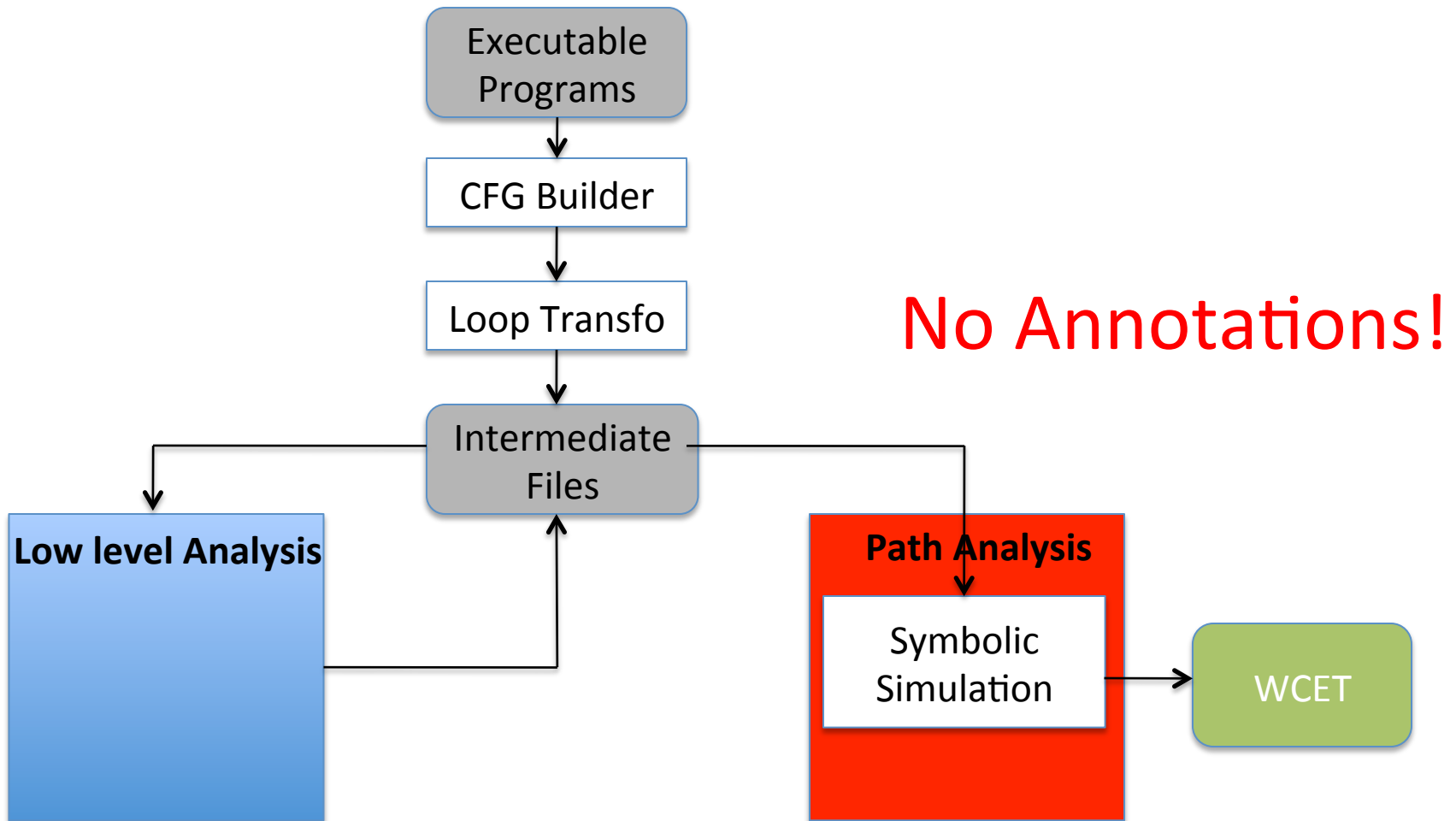
Natural Modularization of Static WCET Analysis



Path Analysis using ILP

- Simple and elegant
- **Manual**: users to provide loop/recursion bounds and additional constraints to exclude infeasible paths
 - Information used is not verified
 - This task is not always trivial
 - Can be error-prone
 - Users might not know of such information

Our Target



Challenge 1: Complicated Loops

- Some patterns for complicated loops:
 - Triangular loops
 - Down-sampling
 - Amortized loops
 - No closed form (but terminating)
- They challenge the aggregation process
- Two options:
 - Unrolling: accurate but not scalable in general
 - Loop Abstraction (e.g. loop invariant or fixed-point computation): more scalable but not accurate

Challenge 2: Infeasible Paths

- Good detection of infeasible paths concerns path-sensitivity
- In theory, **intractably** many infeasible paths
 - Providing annotations for them is not plausible
- In ILP practice
 - Hard to come up with annotations for infeasible paths which stretch over loops and nested loops

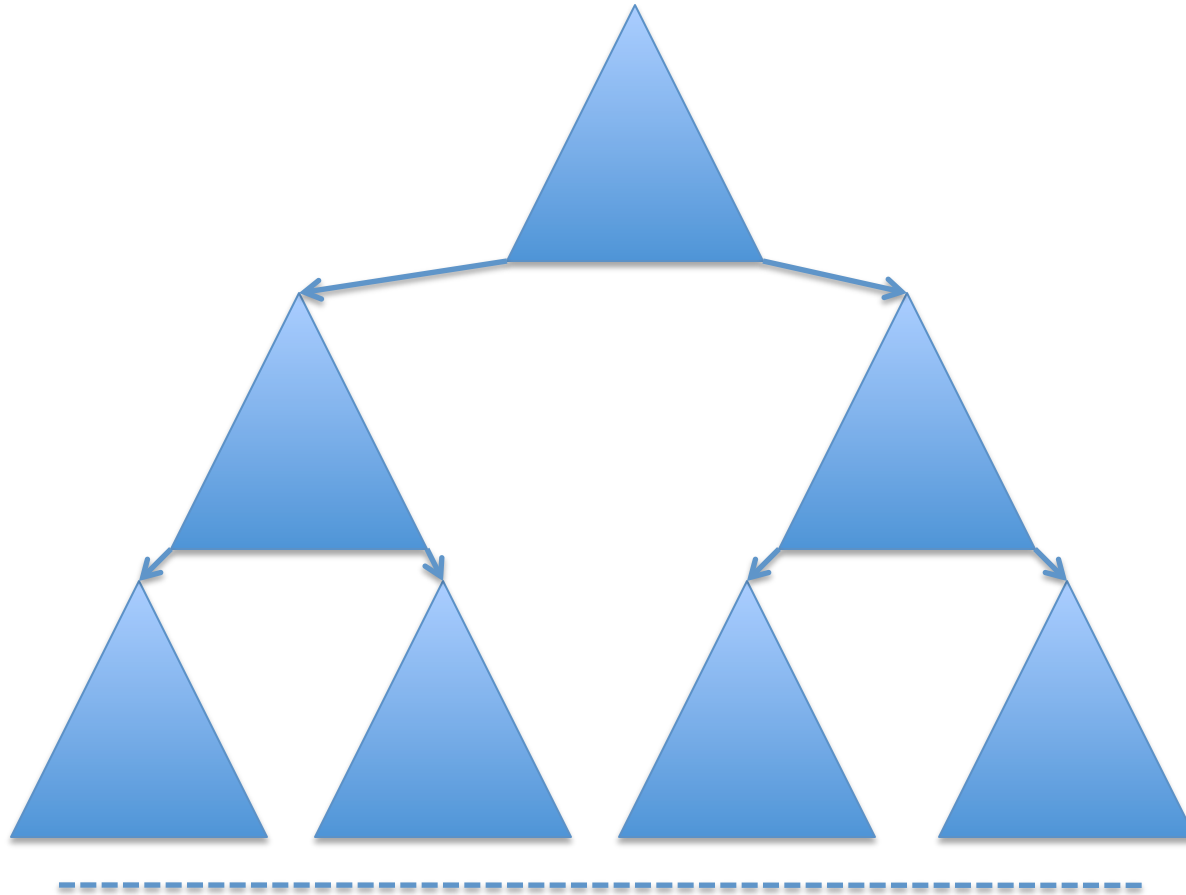
Our Approach

- Symbolic simulation as a brute-force method
 - Loops are unrolled
 - We attempt path-sensitivity
 - Similar to running a program but we are proving it
 - Can be widely applied to different programs and problems
- **Question: how to make this scalable?** In general, symbolic simulation is:
 - At least proportional to the execution of the WCET path
 - Very expensive as
Estimated #states = $2 \wedge \#states_per_average_ground_run$
- In short, we need to deal with the state explosion problem of the symbolic tree in an **ANALYSIS** problem
- **Empirically, we overcome both issues mentioned above**

Our Approach

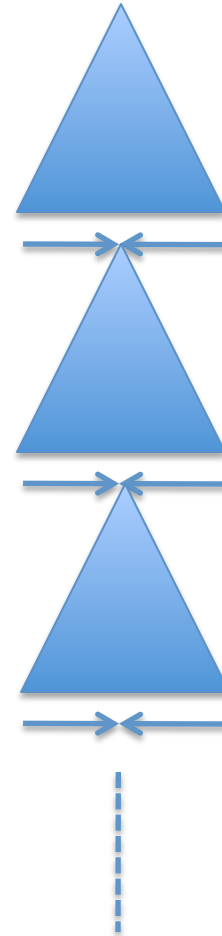
- Iteration Abstraction
 - Path merging (as in [Lundqvist99] and [Gustaffson05])
 - We **only** perform at the end of each loop body
 - We use **polyhedral domain**
- Compounded Summarization with Interpolation
 - We are summary-based
 - Interpolants tell us when we can **safely** reuse
 - Compounded both horizontally and vertically
- Witness Path
 - Witness path conditions tell us when we can **precisely** reuse (i.e. strengthen the interpolant)

Naïve Simulation Does Not Scale



Iteration Abstraction

Multiple contexts are merged into one

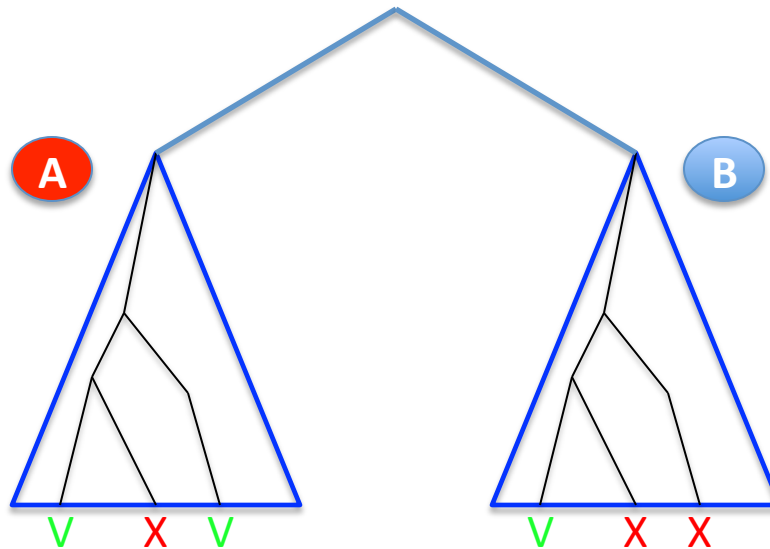


Iteration Abstraction

- Similar to abstract execution[Gustafsson05]
 - They used interval domain
 - We use polyhedral domain (convex hull)
 - First introduced to program analysis by [P. Cousot and N. Halbwachs, POPL'78]
- In general, we might lose information due to abstraction
- Fortunately, most variables affecting control flows of the program are transformed linearly
- Unresolved problems:
 - The depth of the tree is still the depth of the longest path
 - # paths are still exponential wrt # branches outside loops

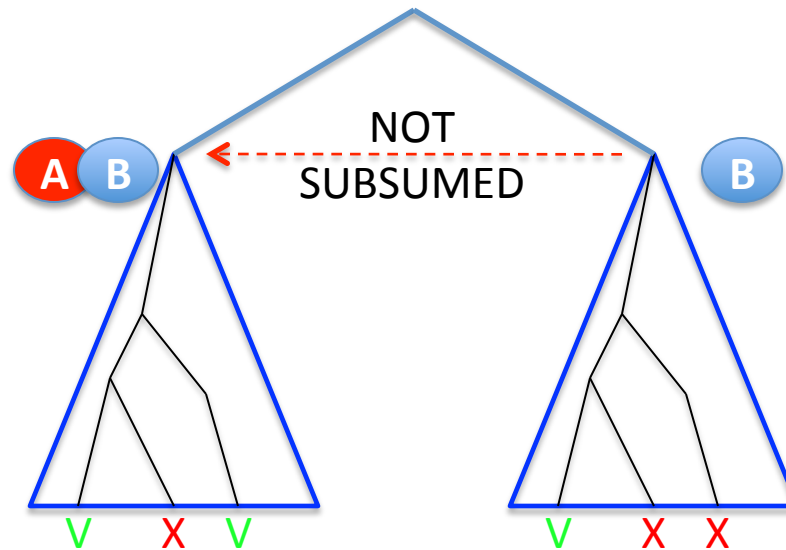
Summarization with Interpolation

A and B are sibling sub-trees (same program point, different context)



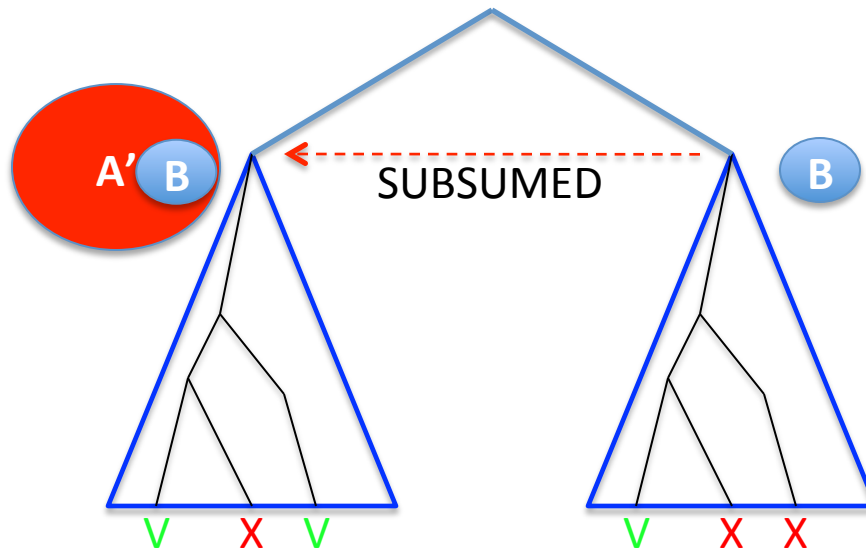
Summarization with Interpolation

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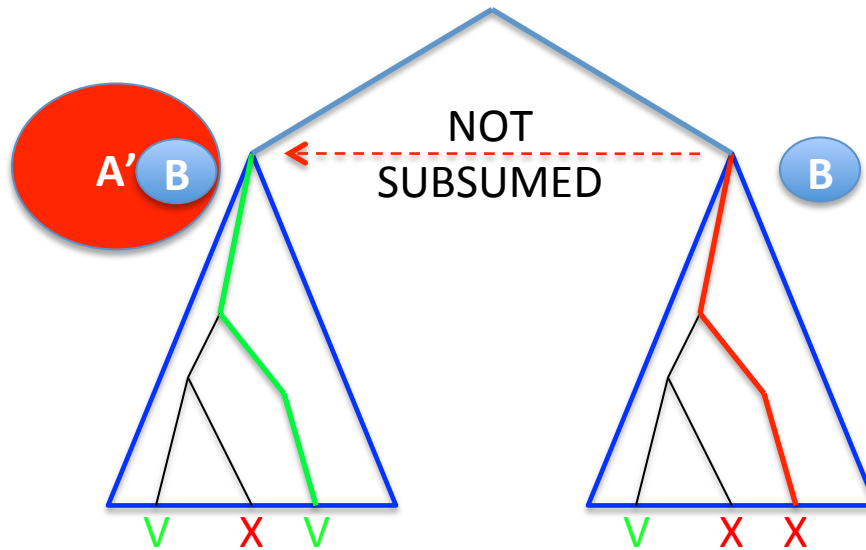
Summarization with Interpolation

A and B are sibling sub-trees (same program point, different context)



Generalize A (to A') while **preserving infeasibility**: B has no more feasible paths than A

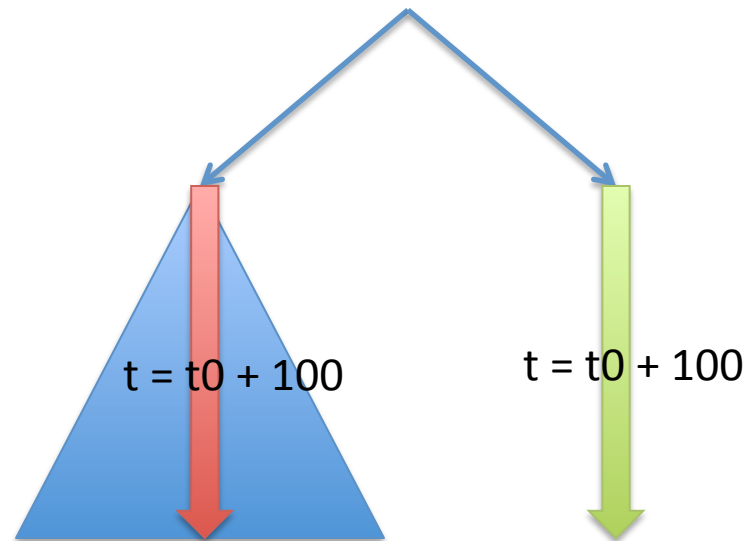
Witness Paths



- Witness path depicting best found solution for sub-tree A
- Mirror path in sibling sub-tree B
- Though B can safely re-use the analysis of A, best path of A is in fact infeasible in B

Breadth-wise Reuse of Summarization

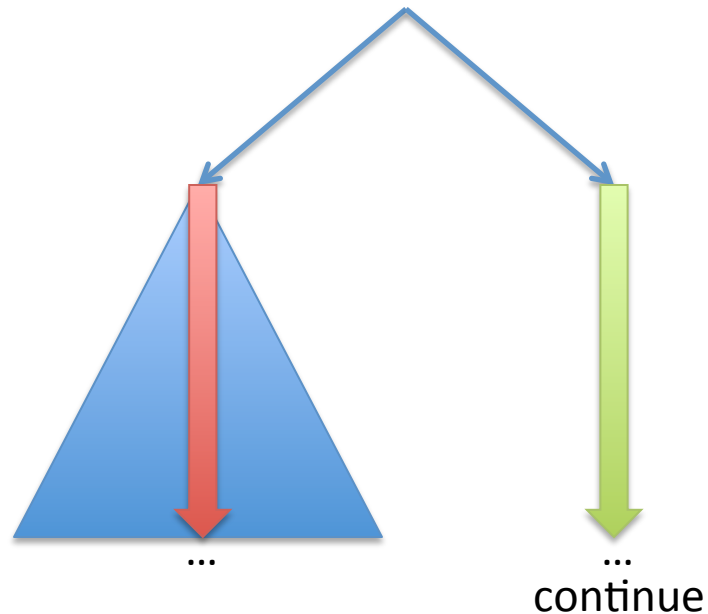
- Use the summarization to produce the solution



The condition for reuse is determined by interpolation and witness paths

Reuse of Summarization

- The leaves of the sub-tree need not be terminal



We need cut-off points and continuation contexts

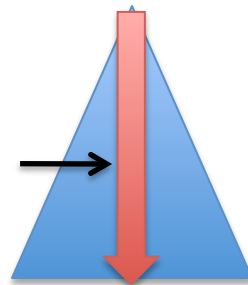
Reuse of Summarization

- To produce continuation context, we require the notion of **Abstract Transformer**
 - Gives an (abstract) input-output relationship for a finite sub-tree
 - Natural cut-off points:
 - Ending point of loop body
 - Ending point of function body
 - Again we compute it using hulling in polyhedral domain
- E.g. `<1> if (*) x++; else x += 2; <2>`
Abstract transformer $\Delta = x + 1 \leq x' \leq x + 2$

Depth-wise Reuse of Summarization

- Reuse is not just for sibling

This includes an **abstract transition** to produce continuation context



Yes, we can reuse here

Reuse of a summarization

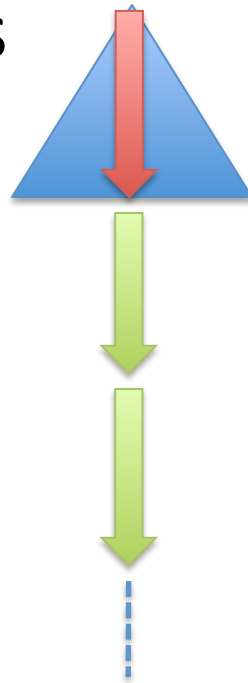


Continue our analysis



Depth-wise Reuse of Summarization

- Very often, the analysis tree for an un-nested loop looks like this



Depth-wise Loop Compression

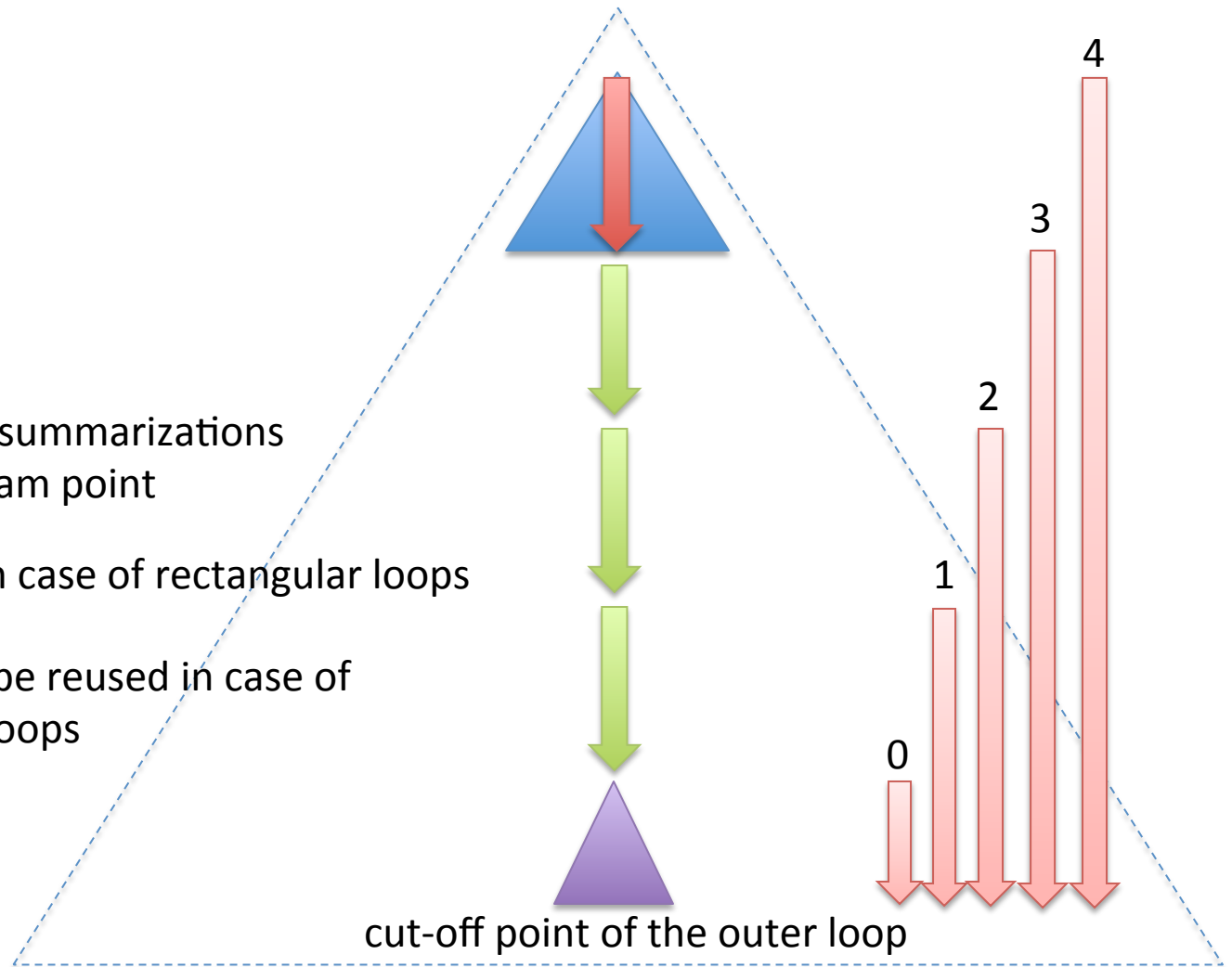
- We just showed the benefits of abstracting and summarizing each iteration of a loop
- **How about summarizing the whole loop?**
 - It benefits when dealing with nested loops

Depth-wise Loop Compression

A serialization of summarizations
for a single program point

4 will be reused in case of rectangular loops

0,1,2,3 will likely be reused in case of
non-rectangular loops



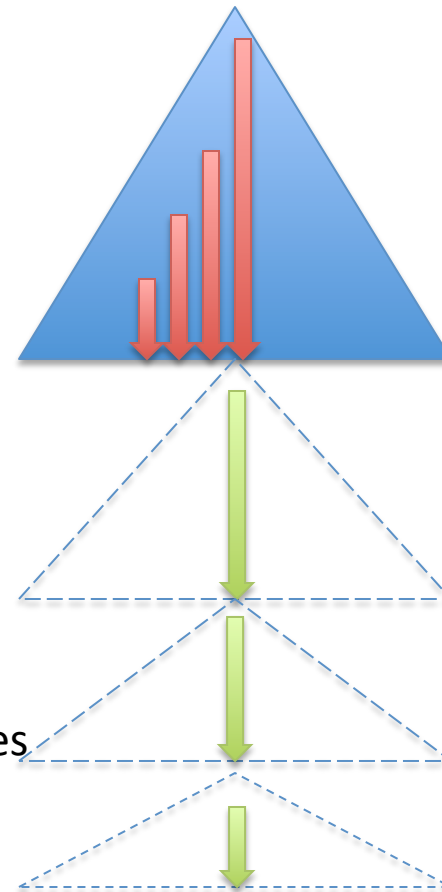
Depth-wise Loop Compression

This is the case for `bubblesort`
(a classic example for triangular loop)

We discover the whole triangle by just (fully) exploring the first iteration of the outer loop

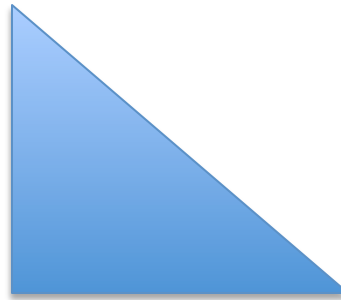
The number inner loop's iterations being explored is just **linear** (Note: only one is fully explored, while the rest are partially explored)

This separates us from other simulation techniques

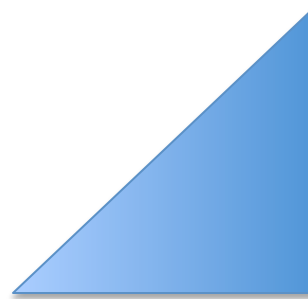


Triangular Loop

- We have done well for this type of triangle

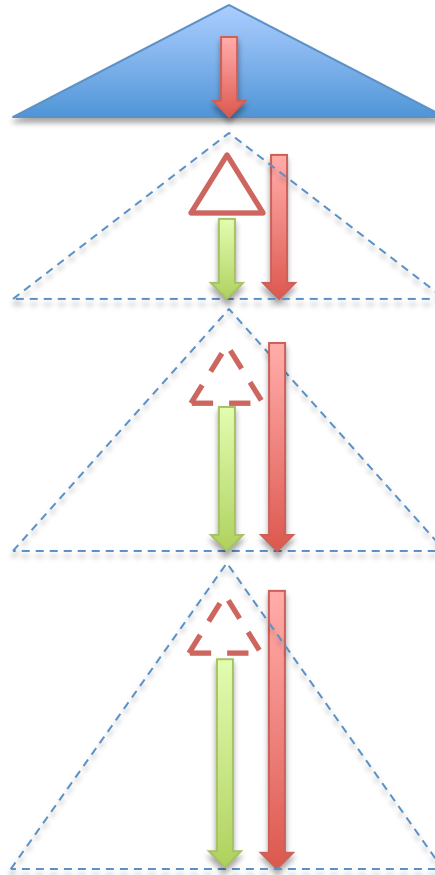


- How about this? (e.g. `insertsort`)



Triangular Loop

It is still **linear**



Experimental Results

Benchmark	Size Parameter	Complexity	WCET	States	Time(ms)	Exact?	
						Manual	Proof
bubblesort	n=25	$O(n^2)$	1648	135	233	Y	N
	n=50		6423	260	701		
	n=100		25348	510	2438		
expint	NA	-	859	519	8247	Y	Y
fft1	n=8	$O(n \log n)$	181	111	446	Y	Y
	n=16		379	176	927		
	n=32		791	287	2197		
	n=64		1661	495	6818		
fir	NA	-	760	108	387	Y	Y
insertsort	n=25	$O(n^2)$	1120	159	387	Y	N
	n=50		4120	309	1504		
	n=100		15745	609	7542		
j_complex	NA	-	534	165	491	N	N
ns	n=5	$O(n^4)$	2655	63	59	Y	Y
	n=10		35555	103	116		
	n=20		522105	183	344		
nsichneu	NA	-	281	334	15542	Y	N
ud	NA	-	819	487	1137	Y	Y

Experimental Results

Benchmark	Size Parameter	Complexity	WCET	States	Time(ms)	Exact?	
						Manual	Auto
amortized	n=50	O(n)	394	95	287	Y	Y
	n=100		792	186	1035		
	n=200		1590	339	4057		
two_shapes	n=50	O(n ²)	2199	259	497	Y	Y
	n=100		8149	509	3235		
	n=200		31299	1009	19839		
non_deter	n=25	O(n ²)	3904	129	59	Y	Y
	n=50		15304	242	116		
	n=100		60604	467	344		
tcas	NA	-	99	6020	15925	Y	Y

Exactness

- Meaning?
 - It's the best a path analyzer can do
 - Implication: want a better bound? improve our low-level analysis
- Proof?
 - Sometimes it is achievable

Proof of Exactness

- Case 1: Single-path programs
 - Power of the abstract domain and/or the theorem prover plays an important role
- Case 2: Multi-path programs
 - The solver is complete wrt the witness condition of the worst-case path and
 - The worst-case path involves no “destructive merges”
 - No loop or no path merging due to loop
 - There are path merging, but they are not lossy ([Thakur08])

Conclusion

- Fully automated WCET path analysis
 - The bound is proved safe wrt to what the low-level analysis component has produced
- The complexity of the analysis can be asymptotically better than a ground run
- Many times, we get exact bound, even for programs with complicated loops
 - Sometimes we have a proof of exactness

Thank you!

Question?